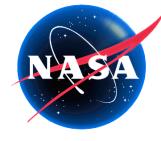




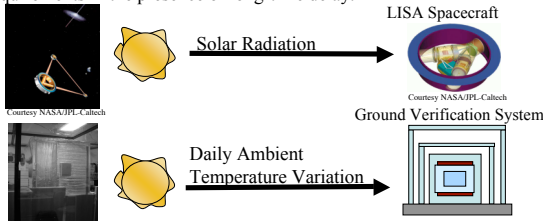
Active Thermal Control Experiments for LISA Ground Verification Testing

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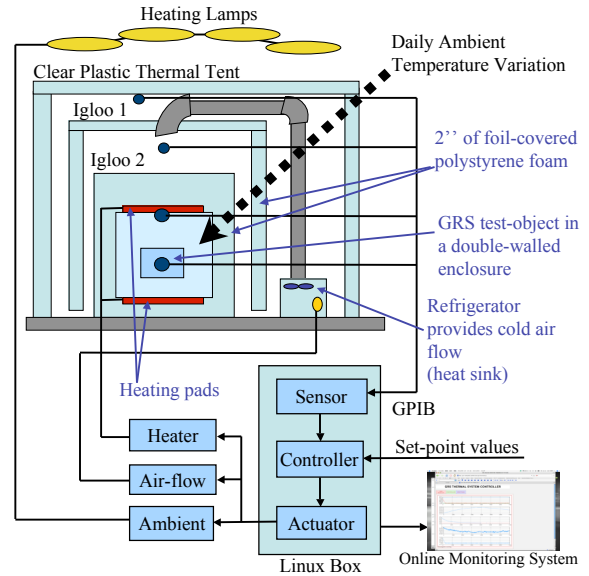
MOTIVATION & OBJECTIVE

- Thermal noise due to solar irradiation, or temperature gradients across the proof mass housing is expected to be significant disturbance source to the LISA noise budgets:
 - The total acceleration disturbances to each proof mass $< 3 \times 10^{-15} \text{ m/s}^2 \sqrt{\text{Hz}}$ over 0.1 mHz to 1 Hz
 - Optical path length variations on each optical bench $< 40 \text{ pm}/\sqrt{\text{Hz}}$ over 0.1 mHz to 1 Hz
- A thermal control system is being developed for LISA GRS ground testing which could be used as in-flight thermal control of the LISA spacecraft to compensate solar irradiate 1/f fluctuations.
- For spacecraft the very limited thermal mass calls for an active control system which can simultaneously meet disturbance rejection and stability requirements in the presence of long-time delay.



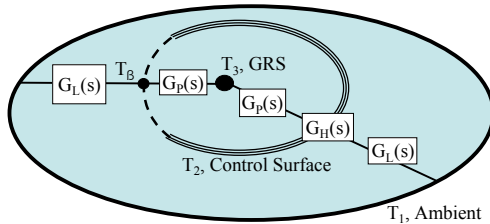
LISA Thermal Stability: $3 \times 10^{-5} \text{ K}/\sqrt{\text{Hz}}$ for $f > 0.01 \text{ mHz}$
 • Low frequency sinusoidal disturbance input
 • Time-delays

EXPERIMENTAL SYSTEM

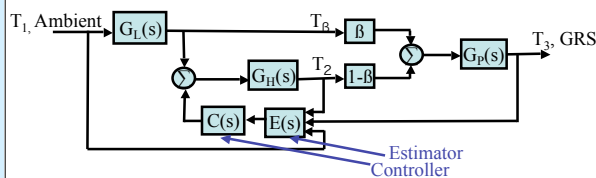


CONTROL SYSTEM DESIGN AND SYNTHESIS

First-order model



Feedback control block diagram of the entire system



FUTURE WORK: Disturbance Rejection Control for Nonlinear MIMO Time-delay Systems

Nonlinear MIMO TDS

$$x(k+1) = f(x(k), u(k-\tau))$$

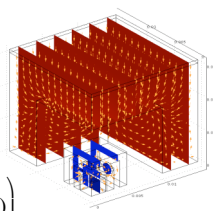
$$y(k) = g(x(k))$$

where $x(k) \in \mathbb{R}^n, u(k) \in \mathbb{R}^m$

The controller minimizes the following cost function.

$$J = E \left(\sum_{k=0}^{\infty} x^T(k) Q x(k) + u^T(k) R u(k) \right)$$

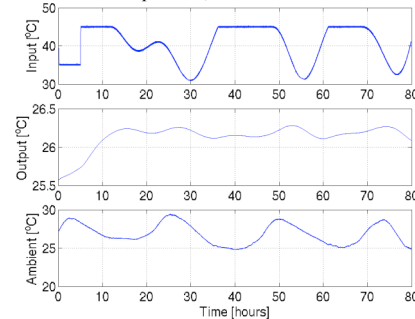
3-D Thermal Model



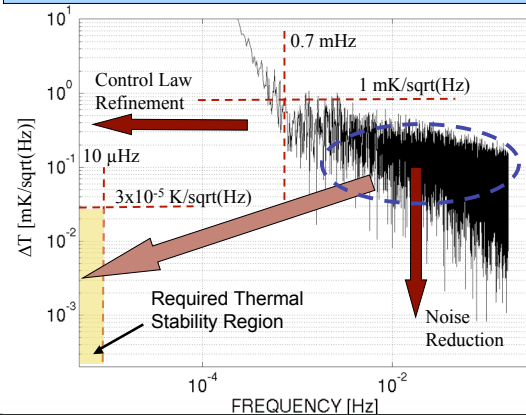
EXPERIMENTAL RESULTS

Time-domain: 80-hour test

- The control system (PI + Smith's regulator) is activated.
 - Input = heating pad temperature
 - Output = GRS test-object temperature
 - Ambient = ambient temperature, which is the disturbance source



Frequency-domain: Stability = $1 \text{ mK}/\sqrt{\text{Hz}}$ for $f > 0.7 \text{ mHz}$



CONCLUDING REMARKS

- Suppressed the ambient temperature variations by a factor of 1,000 down to below 1 mHz using a simple control law and low-cost thermal insulations: $1 \text{ mK}/\sqrt{\text{Hz}}$ for $f > 0.7 \text{ mHz}$
- To satisfy the LISA thermal stability requirements 1) measurement noise reduction and 2) control law refinement are necessary
- Next problem: regulating control for non-linear MIMO time-delay systems

Reference

- [1] S. Higuchi, G. Allen, W. Bencze, R. Byer, A. Dang, D. Lauben, S. Dorlybounxou, J. Hanson, L. Ho, G. Huffman, F. Sabur, K. Sun, R. Tavernetti, L. Rolih, R. Van Patten, J. Wallace, S. Williams, "High-stability temperature control for ST-7/LISA Pathfinder gravitational reference sensor ground verification testing," *Journal of Physics: Conference Series*, 32:125-131, 2006.